

## 10. PREDISPOSITIONS

Prepare the insulated cable ducts for motors and accessories wires (not supplied). Prepare the power plant to the location where you intend to attach the control unit (not necessary in the case of self-powered SOLAR PANEL powered openers) Warning: the power of the high-voltage current must be managed exclusively by a specialized technician. Do not manage yourself the power supply connection 230 / 110V: Danger of Death!

Caution: it is recommended to prepare a disconnection device to be used in case of emergency. Warning: the control unit and activation commands must be installed in a not accessible place and at a height from the ground, not allowing the use by unauthorized persons or children.

## 11. CONTROL BOX INSTALLATION

Fix the bottom of the control unit to the wall or pillar using appropriate screws and plugs (not supplied).

It is advisable to seal any holes to prevent water infiltration, moisture, dust and insects.

It is recommended to provide appropriate compression sleeves (not supplied)

Small control box KONTROL” Small” see pic.39

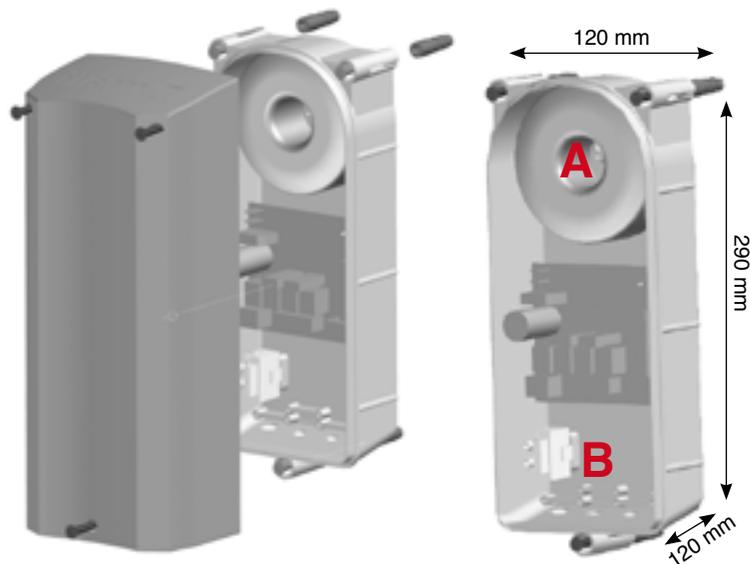
Large control box KONTROL”Large” see pic.40

The control Kontrol “Large” is equipped with a inner protective cover underneath which are inserted the electronic board and the toroidal transformer.

39

### DUCATI Kontrol “small”

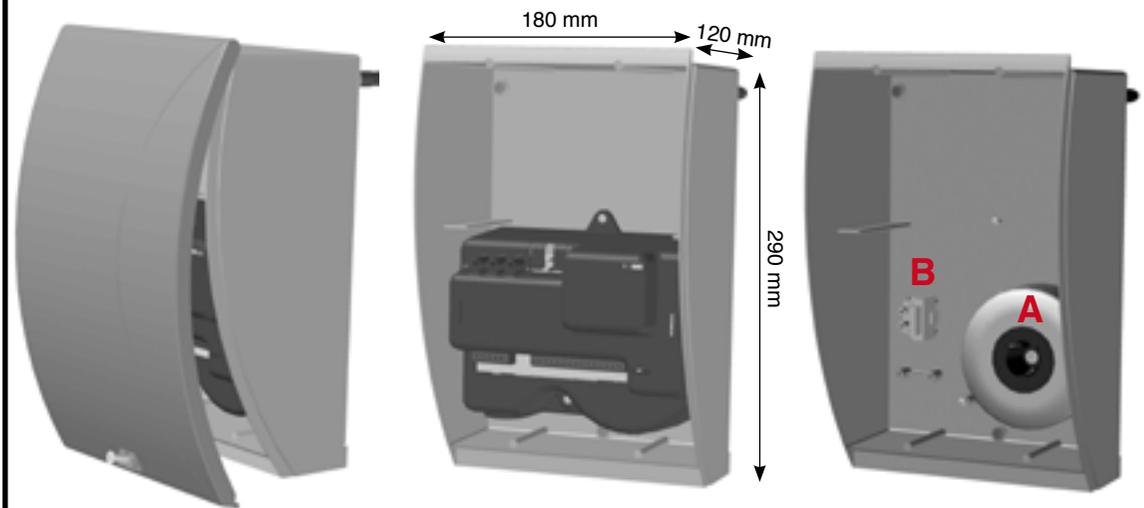
Control Box



40

### DUCATI Kontrol “large”

Control Box



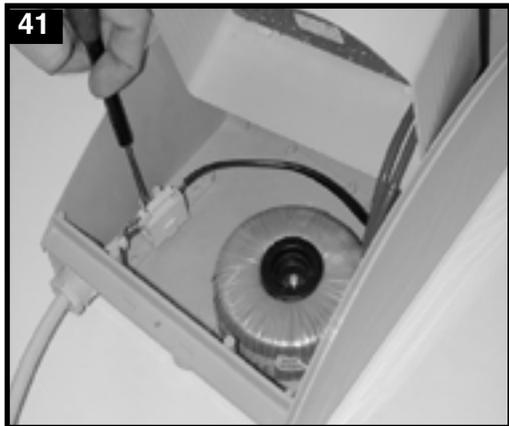
# DUCATI Main AC power supply wiring

## 12. MAIN POWER SUPPLY 230V / 110 V

The main power supply high voltage 230V (110V on request) connection must be performed only by a licensed electrician! Warning: danger of death.  
The power cable is connected to the terminal block / fuse protection upstream of the toroidal transformer (pic.41)  
The transformer is already connected to the PCB. Check for proper connection.  
Connect cables from the transformer to the circuit board.

The toroidal transformer has 3 output cables,  
Black =0 + Yellow= 12V to be used for 12V electronic boards and motors  
Black =0 + Red= 24V to be used for 24V electronic boards and motors

Solar panel powered openers do not require any high voltage connection .Nevertheless, they are always provided with a toroidal transformer and in case of emergency or to recharge the battery the main voltage 230V (110V on demand)can be connected to the terminal block / fuse protection upstream of the toroidal transformer (pic.41)

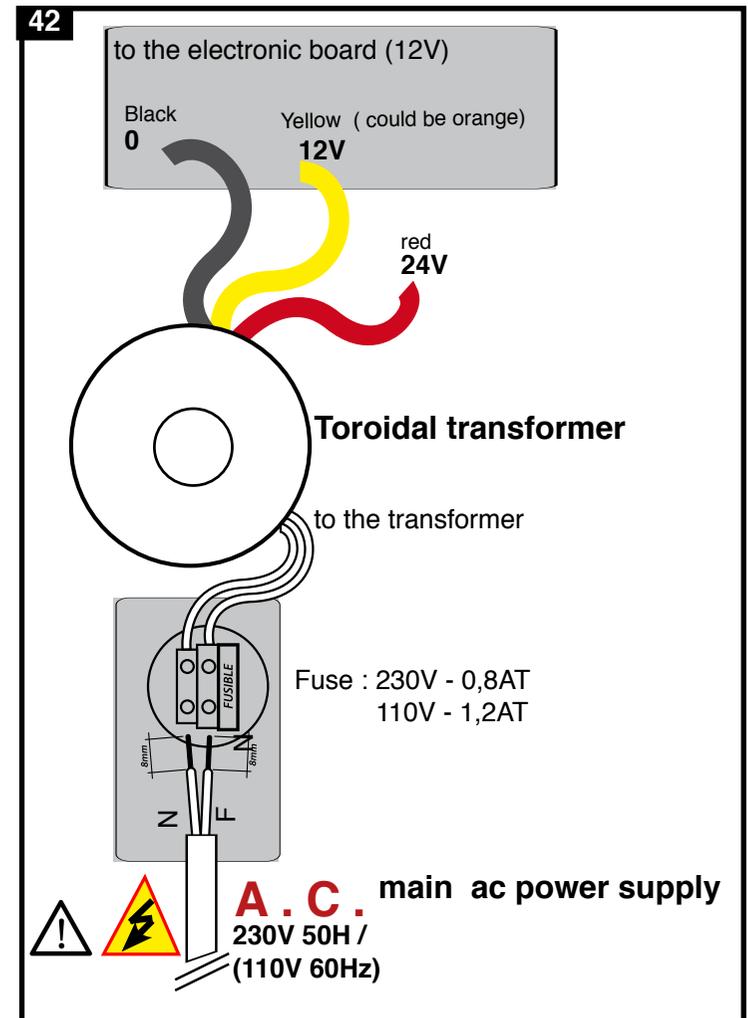


**WARNING!** To prevent damage during shipment, the transformer could be provided not pre-installed in the control panel. it is supplied with a fixing cone and screw to fix it to the bottom of the the control box.

See pic. 39/ 40: Place the transformer in it's correct position (A) and fix it to the bottom of the control box unit using using the special cone support and crew it.

Fix the power supply 230V / 110V connectors terminals with protection fuse in the position (B) of the bottom of the control bozx unit ( see pic. 39-40).

Connect cables from the transformer to the circuit board. Remember:  
The transformer has 3 ouput cables, but for 12V motors only balck and yellow cable must be connected. while red cable (24V must be used in stead of yellow cable only for 24V motor versions)  
Black =0 + Yellow (could be orange)= 12V to be used for 12V motors  
Black =0 + Red= 24V to be used for 24V motors





product  
page [www](#)



only **0,007A** stand-by  
power consumption

**GO GREEN!**  
**ENERGY SAVING  
DEVICE**

■ **CTH48**

12V Electronic control board for 12V motors

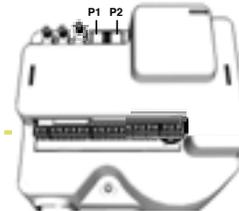
■ **CTH48 /24V**

Electronic control board for 24V motor

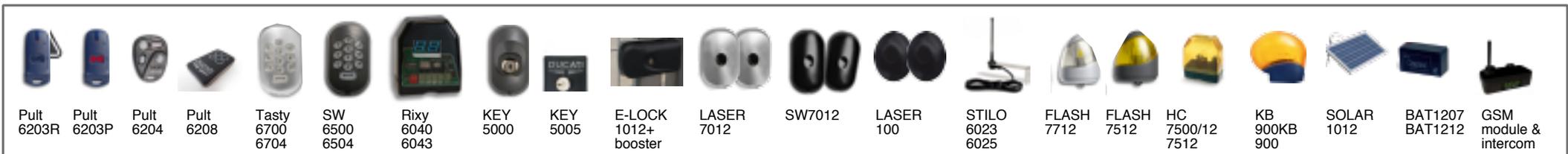
■ **KONTROL9048** Complete control unit:  
large control box with inner battery\* storage  
compartment, CTH48 board and toroidal  
transformer

■ **KONTROL 9048/24V**

Complete control unit: large control box with  
inner battery\* storage compartment, CTH48  
/24V board and toroidal transformer



■ Compatible accessories



Technical data	CTH48	CTH48/24V
Main AC power supply	3 power supply options: a) by 230V (110V version available on demand) by included toroidal transformer b) by ac power supply + back-up battery;c) by back-up battery 12V min 7A+ solar panel 12V min 10W	3 power supply options: a) by 230V (110V version available on demand) by included toroidal transformer; b) by ac power supply + back-up battery; c) by back-up battery 2 x 12V min 7A in series connected + solar panel 24V min 20W
System operating voltage	12V	24V
Compatible with 1 or 2 wings swing gate		√
Transformer protection fuse	√ 10AF	
Protection fuse	0,8A T ( 1,2A T )	
Toroidal transformer		105W
Outputs power connectors	12V	24V
Stand-by energy consumption	0,007A	0,007A
Radio receiver	2 channels: 1 for full opening, 1 for pedestrian opening ( only 1 wing partial opening)	2 channels: 1 for full opening, 1 for pedestrian opening ( only 1 wing partial opening)
Remote control codes storage capacity	20	20
Radio transmission protocol	DUCATI rolling code 433MHz	DUCATI rolling code 433MHz
Remote controls automatic learning		√
On board antenna cable		√
Connectors to wire an aexternal aerial antenna		√
Automatic closure working mode		adjustable pause time up to 100 sec.
Step by step working mode		√ push to open-push to close
Anti-crushing safety system in compliance to the EU Norms EN13241 / EN12453		√ Amperometrical obstacle detection safety system
Asdjustable motor power	√ Turning the potentiometer clockwise will increase motor power and reduce obstacle detection sensibility	
Output for courtesy light (timerized 60 seconds)	√ 12V max 10W	√ 24V max 10W
Output for Electric lock	√ 12V/24V dc output Warning: requires a dc electric lock or a ac electric lock+ booster module to convert ac into dc current	
Input connectors for safety infrared sensors	√ ( NC) while gate is closing if the (NC) contact is opened ( breaking the infrared beam) gate will reverse mouvement and re-open)	
Input connectors for a full cycle opening wired command	√ ( NO contact)	
Input connectors for a pedestrian cycle wired command	√ (NO contact)	
output for blinking warning light	√ 12V max 10W ( blinks slowly while opening, blinks quickly by closing)	
Gear anti-pressure system	√	
Imput for emergency stop button switch	√ NC contact	
Output for remote gate status warning light	√ by gate closed light off, by opening gate light blinks slowly, by open gate light is steady on, by closing gate light blinks quickly	
2 speeds with SOFT STOP	√ during fast speed reverse in case of obstacle detection, by slow speed stops by reaching the end limits or an obstacle	

**Start with the potentiometers positioned as follows:**

- potentiometer **TIME**: turned counterclockwise
- potentiometer **SENS**: turned clockwise
- potentiometer **SLOW**: turned counterclockwise

### TIME

fully turned counterclockwise  
= step-by-step working mode

turned clockwise= automatic closure working mode with pause time up to 100sec.

### SENS

turned clockwise  
= maximum motors power (reduced sensitivity in obstacle detection)

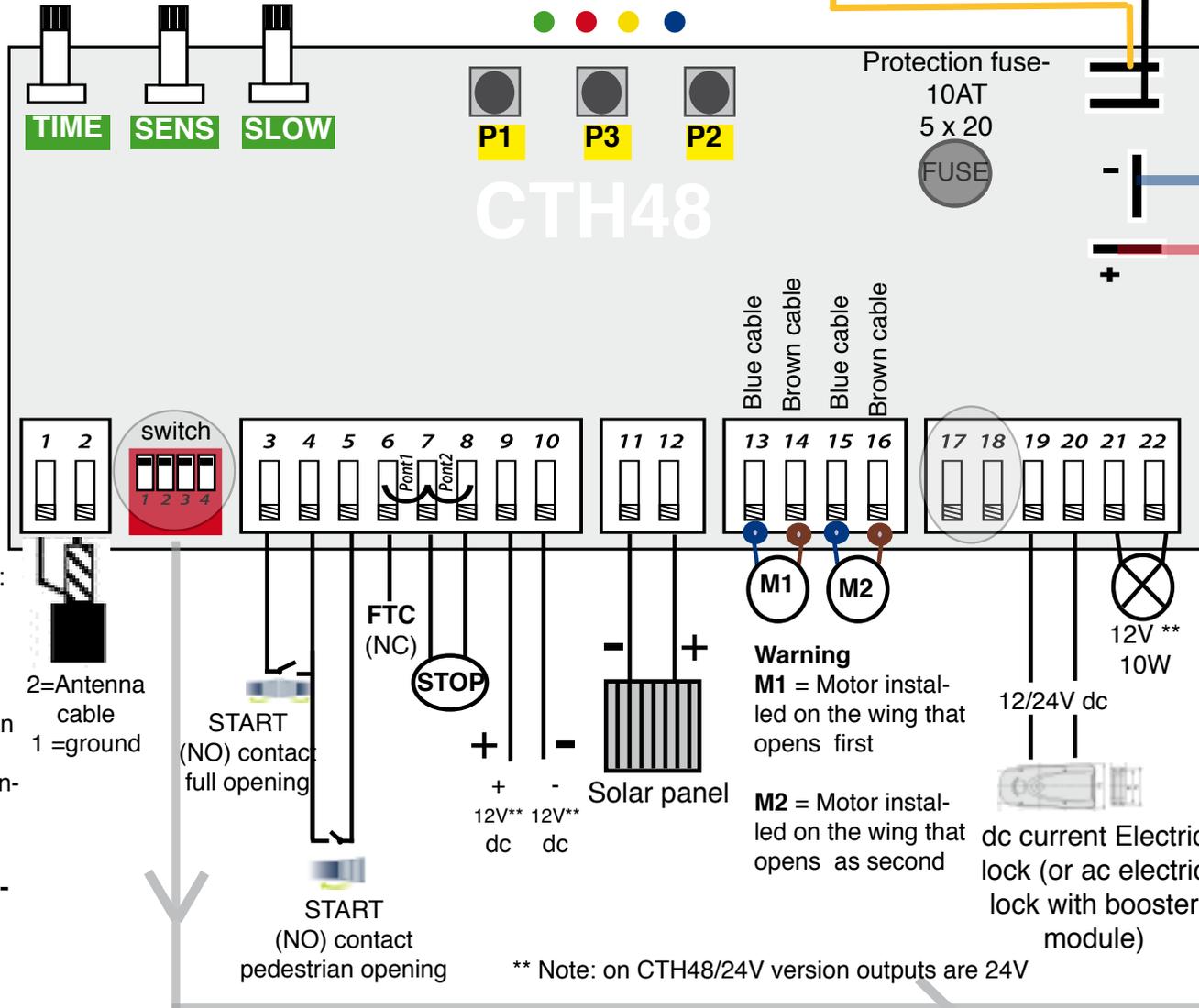
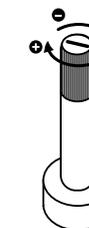
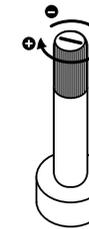
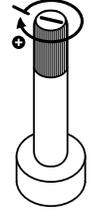
### SLOW

Adjust the starting moment of the second phase (=soft stop/deceleration. Warning: during the first phase in case of touching an obstacle the gate will reverse direction, while in the second phase by detecting an obstacle the gate will stop. Turn counterclockwise to anticipate the second phase

### CAUTION

**SLOW: never turn completely clockwise**

**WARNING !** On CTH48, the movement of the gate takes place in two phases: in the first phase at normal speed, in case of an impact on an obstacle, the direction of travel is inverted. In the second phase (Blue LED lights) at slow speed, in case of an impact on an obstacle, the movement is stopped. This happens even if the softstop is deactivated



Protection Fuse 0,8 AT(1,2AT)



Main AC power supply 230V / (110V)

**How to wire the toroidal transformer:**

**CTH48 (12V):**

use 12V (yellow/orange) cable and 0 = black cable

**CTH48/24V:**

use the 24V red cable and 0 = black cable

Protection fuse-

10AT

5 x 20

FUSE



Battery

Battery cables /connectors  
**CTH48 12V** = battery 12V min.7A

**CTH48 24V** = 2 x battery 12V min.7A in series connected  
Respect polarity:  
+ = positive / - negative

It is mandatory that the electric lock is equipped with a "booster" which converts the 12/24Vdc output voltage of the CTh48 electronic board into 12V ac (standard electric lock's power supply)

### Warning

**M1** = Motor installed on the wing that opens first

**M2** = Motor installed on the wing that opens as second

12V \*\* 10W

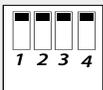
12/24V dc



dc current Electric lock (or ac electric lock with booster module)

\*\* Note: on CTH48/24V version outputs are 24V

switch



**SWITCH N° 1** in **ON** (upper position) = use on 2 wings gate



**SWITCH N° 1** in **OFF** (lower position) = use on 1 wing gate

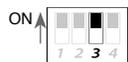


**SWITCH N° 2** in **ON** (upper position) = soft stop will be deactivated and the gate will work only at 1 speed



**SWITCH N° 2** in **OFF** (lower position) = Activate the SOFT STOP function

Note: the soft stop (deceleration) beginning point can be adjusted: by turning the trimmer T3, clockwise it delays the beginning of the deceleration.  
**Warning:** in the first phase (at standard speed) in case of obstacle detection the direction is inverted, while during the second phase (blue LED lights) in case of obstacle detection, the movement is stopped ( the gate will stop reaching the mechanical end limit).



**SWITCH 3** in **ON** (upper position) only if combined with automatic closure (potentiometer T1 must have been turned clockwise to activate the automatic closure function) will enable:

- any impulse/ command (by remote control or wired keyswitch) during the automatic closing operation, will stop and re-open of the gate
- any impulse/ command (by remote control or wired keyswitch) during the timerized pause time (while gate is open), will increase the dwell time for a time equivalent to that programmed.
- maintaining closed the "START" NO contact (for example by connecting a braker), the gate will stay open any command



**SWITCH 3** in **OFF** (lower position), only if combined with automatic closure (potentiometer T1 must have been turned clockwise to activate the automatic closure function) will enable activates the SEMI-AUTOMATIC MODE (or also called ANTI-THIEF MODE)

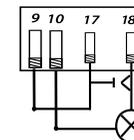
The opener will accept impulses (by remote control or wired keyswitch) during the dwell pause phase, anticipating the closure of the gate. during closure manoeuver an impulse will produce the sequence: STOP-REVERSE OPERATION



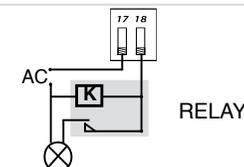
**SWITCH 4** in **ON** (upper position): active courtesy light / garden light lighting time 20sec. you have 2 options of use:

- A1)** NO dry contact becomes NC to activate a small 12V bulb max.10W
- B1)** a relay for any lighting system of higher power. 12V 10W max output terminals 17-18

**A1)** courtesy light 12V max 10W



**B1)** Garden Light powered by 220/110V /110V



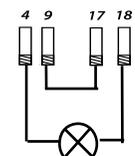
**SWITCH 4** in **OFF** (lower position) \*\*\*activate the remote indication of the gate status .

**A2)** by wiring a LED lamp for example, you can remotely monitor the gate status: open = light on, slow flashing = opening, quick flashing = closing; off = gate closed. Output 12V max 10W lamp to be connected to terminals 17 -18

**B2)** to get the remote gate status signal and an additional command to keep the gate open by 3 wires only follow this instructions:

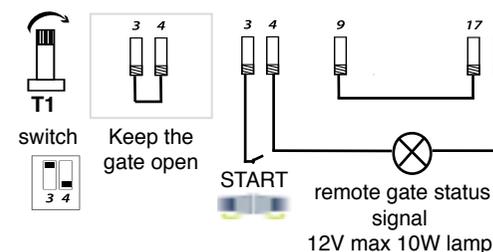
- ( warning: this is possible only with automatic closure mode = potentiometer T1 turned clockwise and switch n° 3 on ON position)
- 1-connect terminal 9 to terminal 17
- 2- connect 3 wires to terminals 3-4-18
- 3- By closing contact between terminal 3 & 4 you will open the gate ( connect a switch)
- 4- By holding the contact between terminals 3 & 4 closed the gate will be kept open (connect a braker)
- 5- \*\*\* connecting terminals 4 & 18 to a 12V max 10W lamp you will get the remote indication of the gate status .

**A2)** remote gate status signal



remote gate status signal  
12V max 10W lamp

**B2 ) ONLY 3 wires to get remote gate status signal and a wired command to keep the gate open**





**WARNING !** All settings have to be made with gate in closed  
**WARNING !** In case the system is powered by solar panel and not from AC mainpower supply, make sure the battery is fully charged

### CTH48 Wiring instructions

1 Antenna ground  
 2 Antenna cable  
**3/4 START:** NO (normally open) contact to command a full opening cycle  
**4 = Common/ ground** (for both full Start and pedestrian start  
**4/5 PEDESTRIAN OPENING START:** NO (normally open) contact to command a pedestrian access cycle (only 1 wing (M1) will partially open.  
**6 FTC** safety infrared photocells NC (normally closed) contact (during closure phase if the infrared light is interrupted by an obstacle, the contact connectors 6-7 is opened and the gate will re-open. The gate will close only once the contact 6-7 is closed)  
**7 Common/ ground** (for both Photocells and emergency stop contacts)  
**8 STOP:** emergency gate stop command. NC (normally closed) contact  
**9 + 12V dc positive power output** (photocells or any device max 0,5A)  
**10 - 12V dc negative power output** (photocells or any device max 0,5A)  
**11 -12V dc negative power input from solar panel**  
**12 + 12V dc positive power input from solar panel**  
**13 M1** motor (actuator) **blue cable** (M1=motor that opens first)  
**14 M1** motor (actuator) **brown cable** (M1=motor that opens first)  
**15 M2** motor (actuator) **blue cable** (M2=motor that opens as second)  
**16 M2** motor (actuator) **brown cable** (M2=motor that opens as second)  
**17/18** 2 possible uses:  
 A) with switch N ° 4 in ON position, connect a timerized garden light  
 B) with switch N ° 4 in OFF position, connect a light (12V max 10W) to be used as remote warning light of the gate status. Light on = gate open; light off = gate closed; blinks quickly by closing gate; slowly by opening gate  
**19/20** Electric lock 12V dc output (warning: ac electric lock require additional booster to transfor dc current into ac current)  
**21/22 Blinking light** 12V 10W max  
**Battery Connectors** (+/-) = connect directly to a back-up battery respect polarity: += positive / - = negative  
**POWER SUPPLY FROM transformer:**  
 CTH48 12V: connect to the power supply connectors on the back of the board the wires : cable Black( 0) + cable yellow /orange(12V) from transformer. No polarity to be respected.  
 CTH48 24V: connect to the power supply connectors on the back of the board the wires : cable Black( 0) + cable red (24V) from transformer. No polarity to be respected.

**CAUTION:** we recommend to test the system fist avoiding immediate installation of infrared safety system. Only after having tested the gate opener works correctly you can add additional complementary accessories as the infrared safety system.

**CAUTION:** if you power the system by solar panel, in order to reduce the energetical absorbtion, we recommend to use reduced consumption photocells model SW7120 / LASER7120 or LASER 100



**Warning:** If you do not connect any photocell (infrared safety sensor) keep the **FTC** photocell infrared contact closed by the supplied electric bridge placed on connectors **6 & 7 (NC= Normally closed contact)**. If the contact gets open and no photocells are wired the gate opener will open but not close.

**PHOTOCELLS - FTC Contact** how it works:

photocells are optional safety devices that are active only in the closing cycle of the gate. Interrupting the infrared beam during the closing maneuver will result in reverse and immediate reopening of the gate.



**Warning:** If you do not connect any Emergency STOP button keep the contact closed with the supplied electric bridge placed on connectors **7 & 8 (NC= Normally closed contac)**.

If the contact gets open and no the gate opener will stop working.

**CAUTION: M1** = Motor installed on the wing that opens first

**M2** = Motor installed on the wing that opens as second

**CAUTION: use on single wing gate:** wire the motor as M1

**CAUTION:: use on gates opening towards outside (push-to-open)**

You must reverse motor cable polarity ( reverse blue-brown cable for M1 and same for M2)

### PUSH BUTTONS

**P1** = **FULL OPENING CYCLE.** Push button to store or cancel the radio transmitters (FOB) codes on the electronic board. This button is used to memorize a remote control button used to command full opening cycles.

**P2** = **PEDESTRIAN ACCESS CYCLE.** Push button to store the radio transmitters (FOB) codes on the electronic board. This button is used to memorize a remote control button used to com-mand pedestrian opening cycles only. M1 actuator's gate wing will partially open to limit the access to pedestrians only.

**P3** = **PHASE SHIFT ADJUSTMENT** push button to adjust the time lag delay displacement between M1 and M2. The adjustment varies the delay time between the leaf M1 and the leaf M2 during the closing phase. The phase shift time remains unchanged during opening. To prevent the doors from overlapping incorrectly a longer phase shift time is necessary when the leaf corresponding to the motor M2 has to travel a greater opening angle than the other wing.

### LED- warnings:

#### Green LED

- steady on=: power supply by AC main power supply
- slow blinking: power supply by battery

#### Red LED

- on after having pressed P1 button = remote control learning mode is activated
- blinking by open gate = gate open by step by step working mode
- steady on by open gate = gate open by automatic closure working mode.
- continuously blinking = by battery power supply the power is lower than 10,5V

#### Yellow LED

- blinking = by battery power supply the power is lower than 11,5 V.

#### Blue LED:

- during a manoeuver = lights up during the second phase (deceleration phase)
- switch on by pressing P3 button= phase shift adjustment mode is activated



### **WARNING !**

CTH48 electronic board divides the movement of the gate in **two phases**: **in the first phase**, at normal speed, in case of obstacle detection, **the gate reverses** the direction of travel. **In the second phase** (=blue LED lights) speed will slow down (SOFT STOP) and during this phase in case of obstacle detection, **the gate stops**. Make sure the gates enter in the second phase before the gate reaches the mechanical end limits.

### POTENTIOMETERS (trimmers)



### **WARNING !**

We recommend the following settings for the first installation to test the system: Start with the potentiometers positioned as follows:  
 trimmer TIME: turned counterclockwise  
 trimmer SENS: turned clockwise  
 trimmer SLOW: turned counterclockwise

#### **Trimmer 1 (TIME) potentiometer to set the working mode:**

- **“step by step” working mode**

Rotating the potentiometer counterclockwise to position “0” you set the “step by step” working mode. In this mode one impulse makes the gate open. the gate will stop by amperometrical obstacle detection. One impulse make the gate close. During opening manoeuver it is not possible to stop the gate by wired or remote controlled command. During closure manoeuver one impulse will stop and re-open the gate.

- **“automatic closure” working mode**

Rotating the potentiometer clockwise you set the pause time before the the automatic closure of the gate. Rotating clockwise the increases the pause timeup to 100 seconds. During opening manoeuver and during pause time the gate will not accept

any command. the gate will automatically close after the setted pause time. You can set additional functionalities by changing Switch 3 position

#### **Trimmer 2 (SENS)**

This potentiometer is used to adjust motor power and sensitivity levels in case of obstacle detection. In position = 0 (trimmer turned completely counterclockwise) = minimal power and high sensitivity in case of obstacle detection. **Turning the trimmer clockwise reduces the sensitivity and increases motor power.** It is recommended to reduce the sensitivity in case of wind gusts or heavy gate. Note: the adjustment sets the levels of the secon phase of the manoeuver ( SOFT STOP) only.

#### **Trimmer 3 (SLOW)**

Regulates the starting moment of the second phase of the manoeuver (SOFT STOP). The CTH48 electronics divide each manoeuver into two phases:

**first phase:** motor starts at standard speed and in case of obstacle detection the travel direction is reversed.

**second phase:** at reduced speed (SOFT STOP) and in case of obstacle detection the gate stops.

The beginning of the second phase starts after 7 seconds from the beginning of the maneuver. By turning potentiometer “SLOW” you can adjust and delay the beginning of the second phase. Turn clockwise to posticipate the beginning of second phase.



It's very important that the mechanical end limit is reached during the second phase. In case of uncorrect adjustment the gate might reach the end limits during the first phase and this will produce the gate reverting the travel direction instead of stopping on the end limits. **Turn potentiometer counterclockwise to anticipate second phase** (SOFT STOP) beginning.

**Caution:** Even if you can deactivate the speed slow down (SOFT STOP) by setting Switch nà 2 in On position, the electronics will always keep dividing the manoeuver in 2 phases. It is therefore mandatory that the 2° phase begins before the gate reaches the mechanical end limit.

### WIRED COMMANDS:

**START:** by wiring a bistable NO switch to connectors 3 & 4 you can command the full opening cycle by a wired command (key switch/ intercom button, or any additional additional button) both wings will open and both wings will close.

**START PEDESTRIAN:** by wiring a bistable NO switch to connectors 4 & 5 you can command the pedestrian opening cycle (M1 actuator's gate wing will partially open to limit the access to pedestrians only).

### REMOTE CONTROLS ( FOB)

**Warning:** control board model CTH48 can storage up to 20 ducati rolling coded remote controls buttons. In case you need to use more than 20 remote controls, you can purchase an extra (optional) Ducati radio receiver (RIXY6040 or RIXY 6043). Warning: only original ducati rolling coded remote controls are compatible.

**A-1) How to memorize a remote control button in the control board memory to command a FULL OPENING CYCLE** (on 2 wings gate both wings will open and both wings will close/ on 1 wing gate the gate will fully open)

**Warning: Gate must be closed and idle** (check the RED LED is switched off).

- 1) on the main electronic board press push button **P1**
  - the red LED will switch on (to confirm you entered the learning mode)
- 2) release **P1**
- 3) Press the remote control button you want to use to operate your gate. Hold the remote control button pressed for at least 3-4 seconds
  - once the main electronic board has stored the remote control the main control's board red LED will blink shortly to confirm remote control button has been stored. Wait for the main board's red LED to switch off.
- 4) You can now use the stored remote control's button to command your gate manoeuver. (Same remote control's button will operate both opening and closing of your gate). Repeat this operation for all desired remote controls.

**A-2) How to memorize a remote control button in the control board memory to command a PEDESTRIAN OPENING CYCLE**

as above point A1, but using P2 instead of P1

**B) How to erase all remote controls from the memory of your control board**

If the electronic board's memory is full or if a remote control is lost, it is possible to erase the stored remotes controls from the memory of the electronic board (attention this process leads to a total loss of memory).

Thereafter, the remote controls must be re-stored on the board.

Warning: Gate must be closed and idle.

- 1) on the main electronic board press push button **P1** and hold it pushed for about 30 seconds until the red LED blinks to confirm all memory has been deleted
- 2) release **P1**

Memorize again the remaining remotes you want to use by following instructions as in point A) here above. Repeat the procedure for each remote control

Um neu zu programmieren die Schritte vom Punkt A von 1-4 befolgen.

### TIME SHIFT ADJUSTMENT ( between 2 wings)

This function allow to adjust the 2 wings automatic pause shift.

Standard setting: M1 starts to open, and M2 starts to open about 4 seconds after M1 and Vice Versa during closure manoeuver.

The adjustment varies the delay time between the leaf M1 and the leaf M2 during the closing phase.

The phase shift time remains unchanged during opening.

To prevent the doors from overlapping during the closing phase, a longer phase shift time is necessary when the leaf corresponding to the motor M2 (the one that closes as first one) has to travel a greater opening angle than the other wing (the one that closed as second one).

The adjustment is required only if the M2 gate wing needs to open with an opening angle greater than M1's Gate wing

**P3** = push and release P3 to enter the phase shift adjustment. the blue LED lights up.

Within 5 seconds:

- Press P1 to increase the shift time. The green LED will switch on at each impulse.
- Press P2 to reduce the shift time. The yellow LED will switch on at each impulse.

Each impulse corresponds to 0,5 seconds increase/ reduction of shift time.

By reaching the minimal/ maximal adjustment the red LED will switch ON to warn you that the limit has been reached.

As you have entered the desired adjustment, wait 5 seconds without pressing any button to confirm the selection.

### Power supply by emergency back-up battery

Use a fully charged 12V min.7A battery

Use the 2 wires welded to the backside of the control board CTH44 to connect the battery to the board.

**WARNING:** respect cable polarity red cable= battery positive pole (+); blue cable = battery negative pole (-)

In case of main ac power supply failure, the back-up battery will ensure autonomous use for up to 4 days.

### Power supply by Solar panel and battery: 100% autonomous use

Use a fully charged 12V min.7A battery

Use the 2 wires welded to the backside of the control board CTH44 to connect the battery to the board.



**WARNING:** respect cable polarity red cable= battery positive pole (+); blue cable = battery negative pole (-)

Connect a 12V min.10W solar panel to the board CTH44 by means of bipolar (outdoor use min. 0,5mmq cable) with the utmost attention to the polarity of the terminals:

**connector n° 11** - solar panel negative

**connector n° 12** + solar panel positive

The solar module should be directed towards the south (see also notes installation and positioning) and in a well-lit place. Avoid shadow zones, which reduce the load capacity considerably.

It is recommended to install the solar panel not over 10-15 meters from the electronic board to prevent unnecessary electrical losses.

The following table shows an estimated calculation of the autonomy in non-ideal weather conditions ( winter cloudy weather) by use of a 10W solar panel and 7A battery.

The autonomy increases in case of use of to larger capacity battery (ex. 12V 12A) and larger solar module (ex. 12V 20W). Instead of using a larger solar module, on CTH44 it is possible to add a second solar panel to increase the charge capacity.



**WARNING:** by increasing the watt of the solar module, the battery capacity must also be increased.

For example: if using 20W 12V solar panel requires a 12V min 12V battery.



**NOTE:** you can also wire main ac power supply through a switch. The AC power supply can be switched on to recharge the battery in case of needs, DO not power the board by both solar panel and AC power supply at same time.

TABLE-	GATE	Stand-by consumption ( A)	daily consumption	Consumption for a complete cycle (open+ close), (A)	Suumption of total n° of daily cycles (open+close)	total daily consumption (A)	average charge of a 10W 12V solar panel (A /hour) in non ideal weather	hypotesis of lixght exposure ( hours/per day)	Total recharge capacity (A)	balance between consumption and recharge
Board CTH48	1 wing	0,007	0,16	0,012	60	0,88	0,3*	5	1,5	+ 0,62
	2 wings			0,024	50	1,36				+ 0,14



6203R 6203P 6204 6202 6208



■ **Model 6203 ROL = 2 buttons rolling coded remote control. Blue with blue button FOB.**

Battery: 1 x 12V C-23A

■ **Model 6203 P = 2 buttons rolling coded remote control. Blue with red button FOB.**

Battery: 1 x 12V C-23A gespeist

■ **Model 6202 = small 2 buttons rolling coded remote control. in blue, yellow, red, black color available.**

Battery: 2 x CR2016 3V

■ **Model 6208 = small 4 buttons rolling coded remote control. white/black color FOB**

Battery: 2 x CR2016 3V

■ **Model 6204 = small 4 buttons rolling coded remote control. black color FOB**

Battery: 1 x 27A 12V gespeist



The DUCATI radio rolling coded transmitters (FOB), featuring a unique “rolling code” radio protocol are compatible with all Ducati rolling coded openers (CTH electronic boards). With over 3 billions of continuously changing combinations, they ensure maximum protection against radio interferences. Frequency: 433,92MHz

Any of the rolling coded remote controls is compatible with all models of rolling coded Ducati’s openers. You can combine and use different remote control model on the same opener

Each transmitter button is factory programmed with a unique code. Ducati’s rolling code remote control cannot be cloned.

Each button on the remote control can be used to operate a different function ( for example tone button to command full opening cycle, and second button to command pedestrian opening cycle) or different openers ( for example one button to command your gate opener and the second button to command a garage door opener

**Warning:** The memory of the control board of your opener can store up to 10-20 codes depending on the model (check the maximal storage capacity of your electronic board). If you need a larger number of remote controls you can purchase an optional external receiver (RIXY6040 o RIXI 6043). The external receiver can be also used to command other brand automatic systems with a Ducati rolling coded remote control.

To operate your “DUCATI” opener with your DUCATI remote control you must memorize the remote control code on the electronic board of your opener. **WARNING:** Operate adjustments and settings only with garage door or gate in closed position.

### **A) How to memorize (store) the remote control code inside the electronic board of the opener for full opening cycle**

The door must be closed and idle.

- Press button P1 on the electronic board. The red LED switches on.

- Release button P1 and immediately press on the buttons of the remote control that you wish to use to operate the device. Hold the remote button pressed for about 4 sec. - the LED light on the electronic board will quickly blink to show the procedure has been completed. Wait until the LED switches off.- Press again the memorized remote control button, the opener will start an manoeuvre

### **A2) How to memorize (store) the remote control code inside the electronic board of the opener for pedestrian opening cycle ( only 1 wing will partially open)**

Please check the specific instructions for each specific electronic board model.

to resume:

On board model CTH41: this feature is not available.

On board model CTH42: like the procedure at point A1, but use the **J1** button instead of the P1 button

On board model CTH44: follow the instructions of point A1, but instead of just pressing P1, press and hold **P1 and simultaneously press P2** and then release both buttons.

On board model CTH48: follow the instructions of point A1, but use the **P2** button instead of the P1 button

**Warning:** when opening your gate in pedestrian mode, the gate must be closed with pedestrian mode before to proceed with a full opening cycle command.

### **B) How to erase the codes from the control board ( total loss of all previously stored remote controls)**

To deactivate any unwanted remote, erase its memory from the electronic board of your opener as following (all remote control codes memorized will be delated):

- The door must be closed and idle.

- Press button P1 for about 30 sec. until the red LED blinks

- Release P1. All codes have been erased and the memory of your control board is ready to memorize new remote controls ( follow instructions as on point A